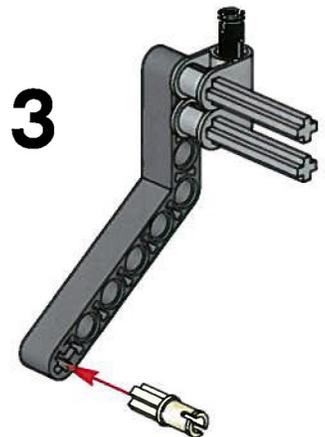
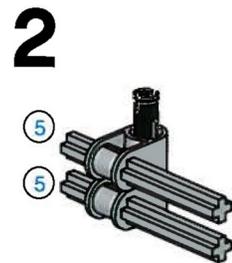
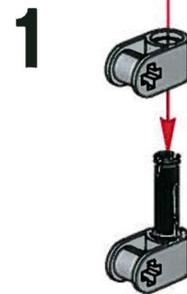
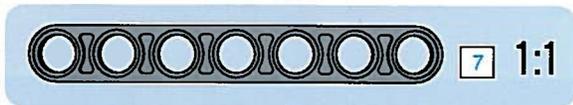
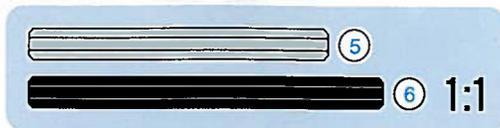
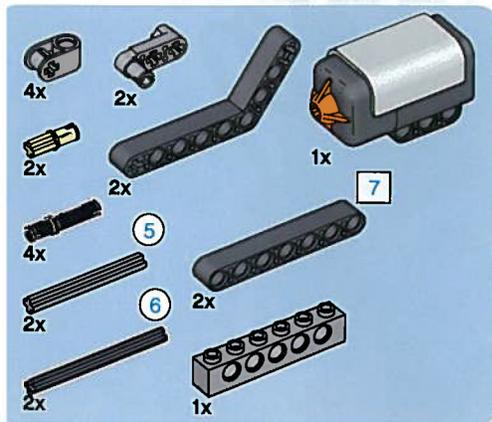
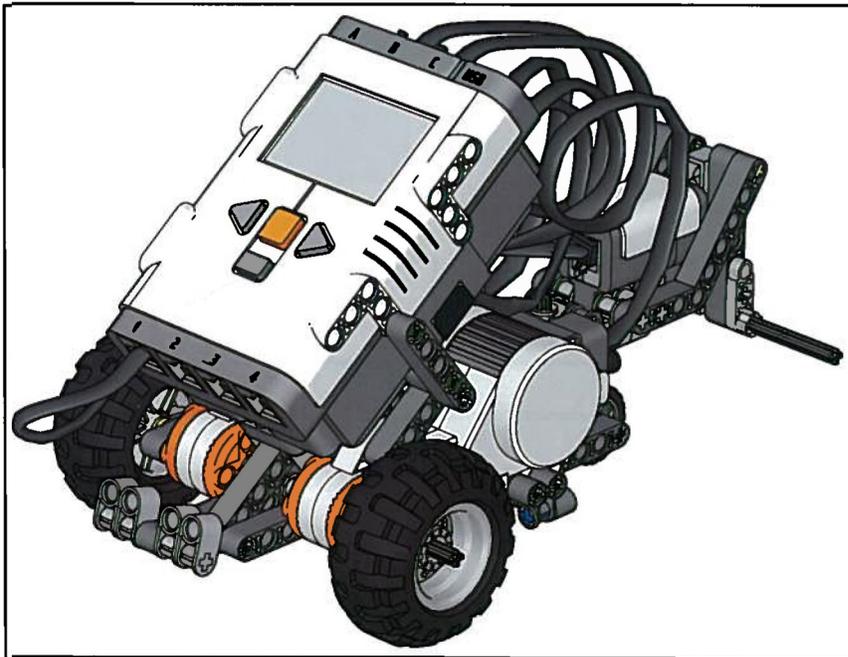


Assemblage du capteur tactile LEGO NXT

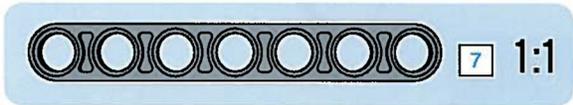
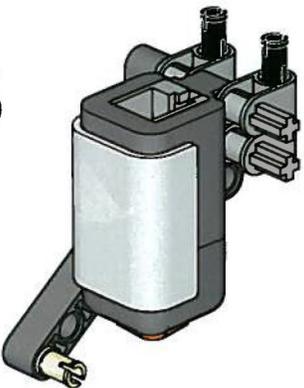




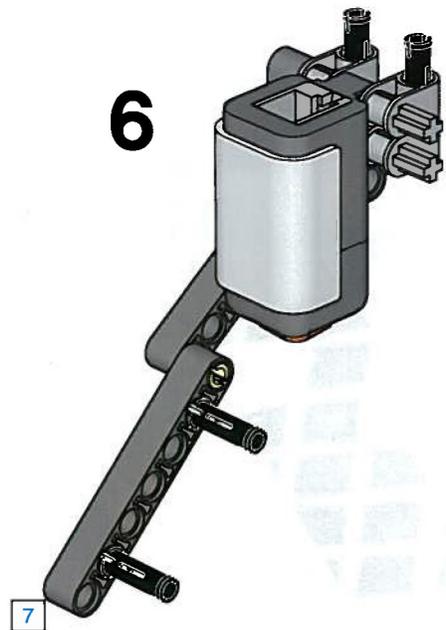
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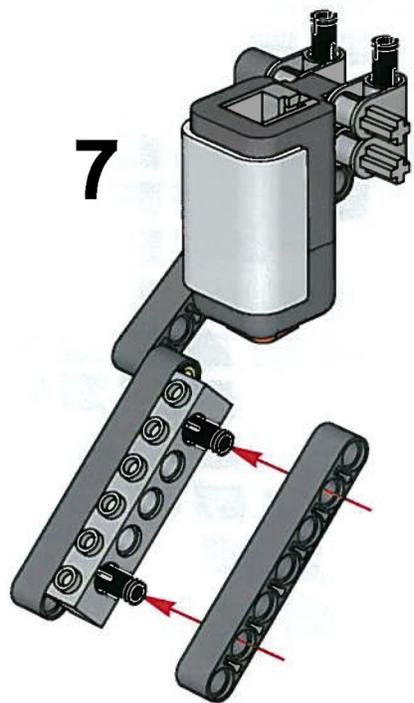
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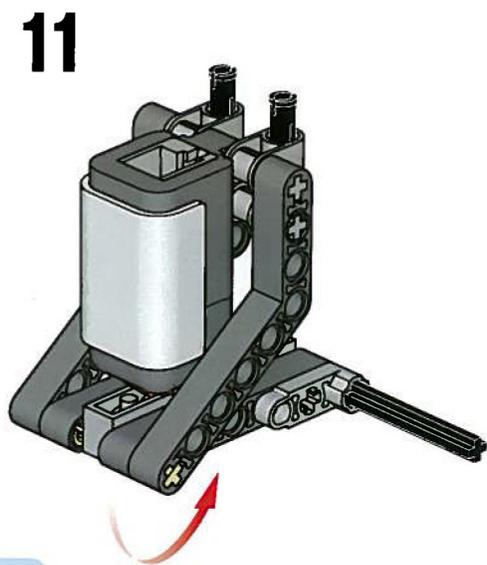
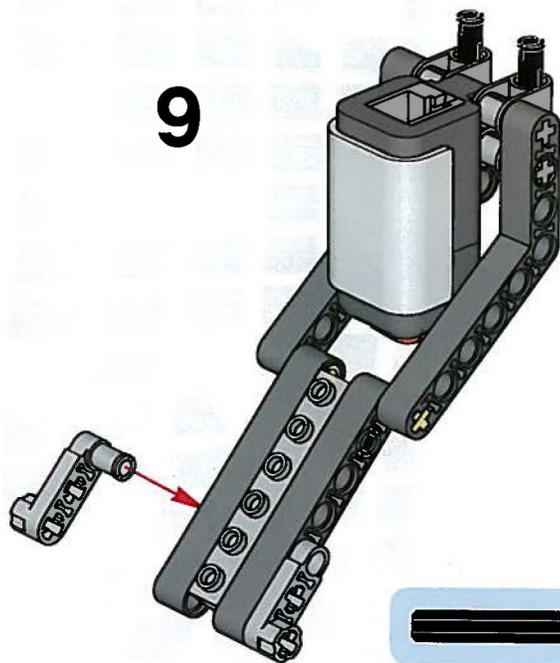
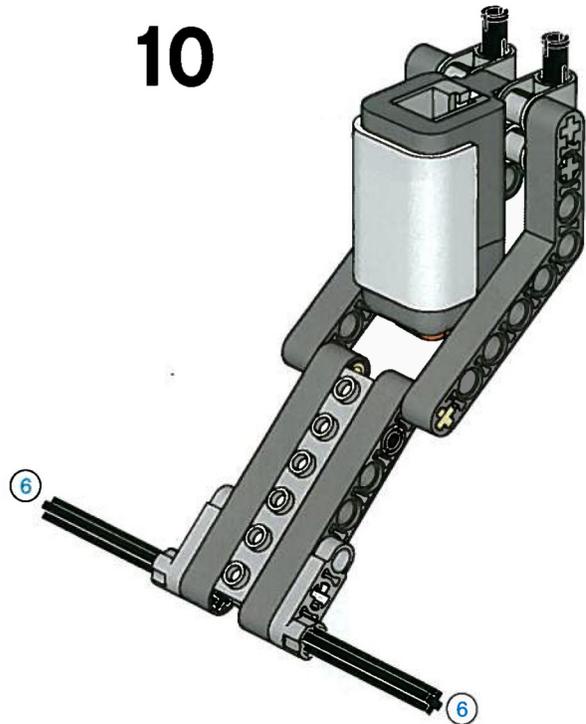
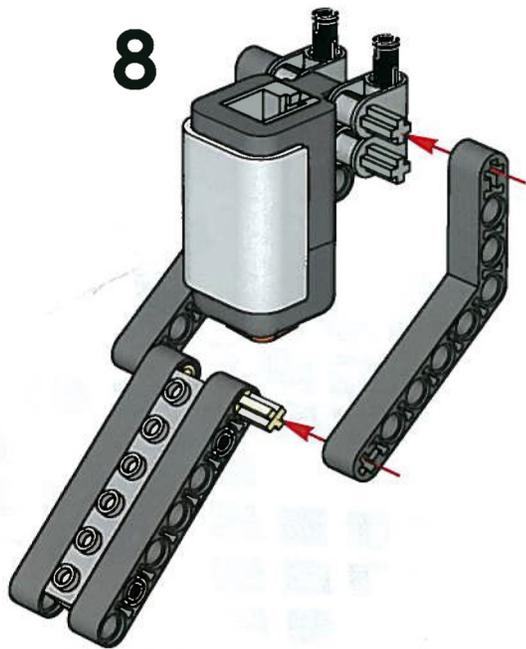


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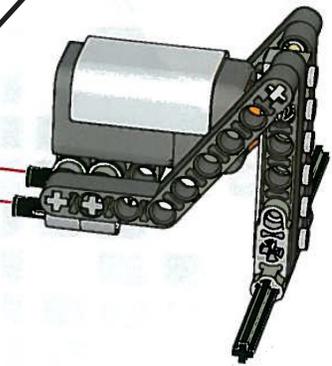
7







Le détecteur tactile se glisse à l'arrière du robot, juste au dessus de la roue arrière



Branchez le fil du détecteur tactile dans l'entrée numéro 1 qui se situe en avant du module de contrôle

